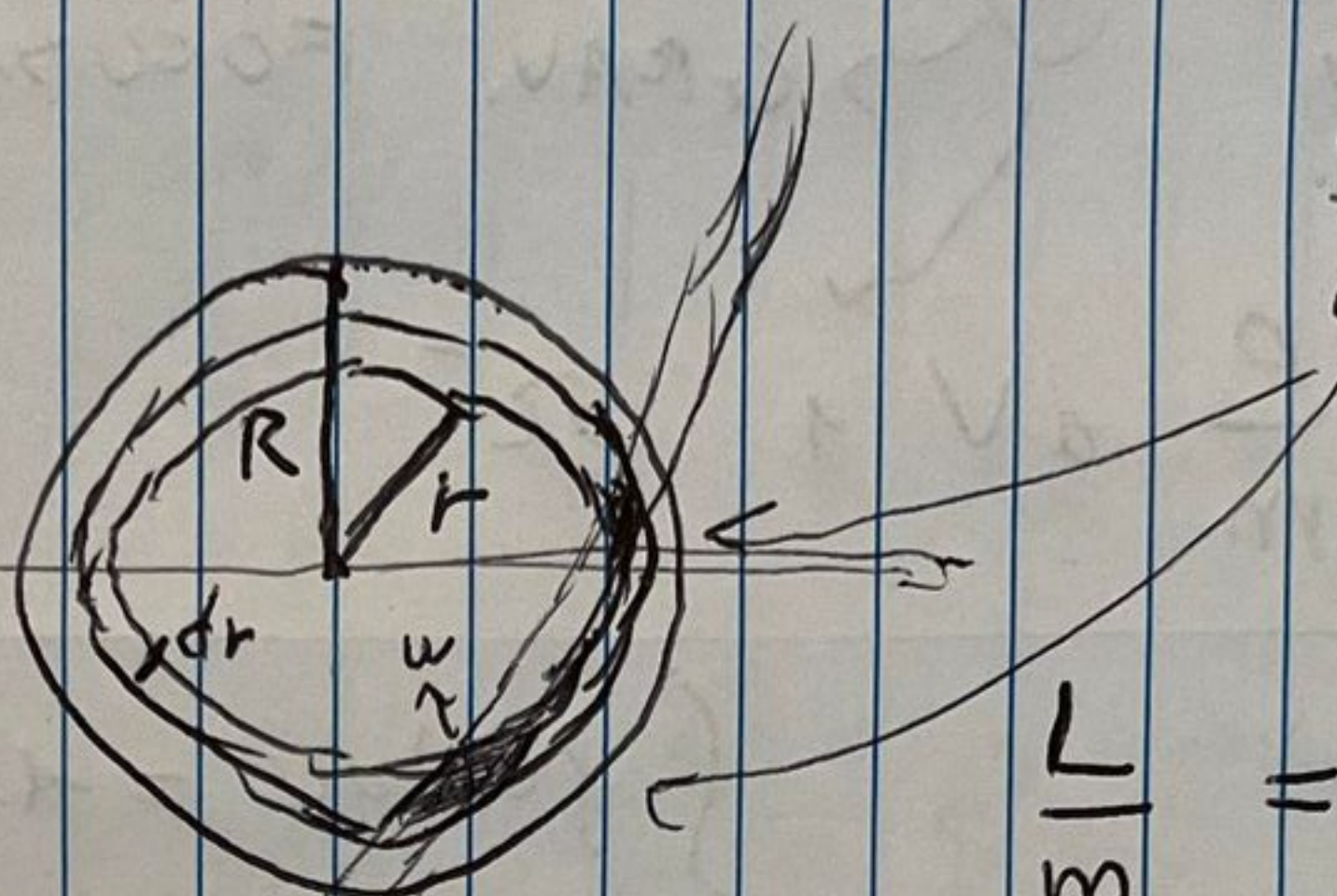
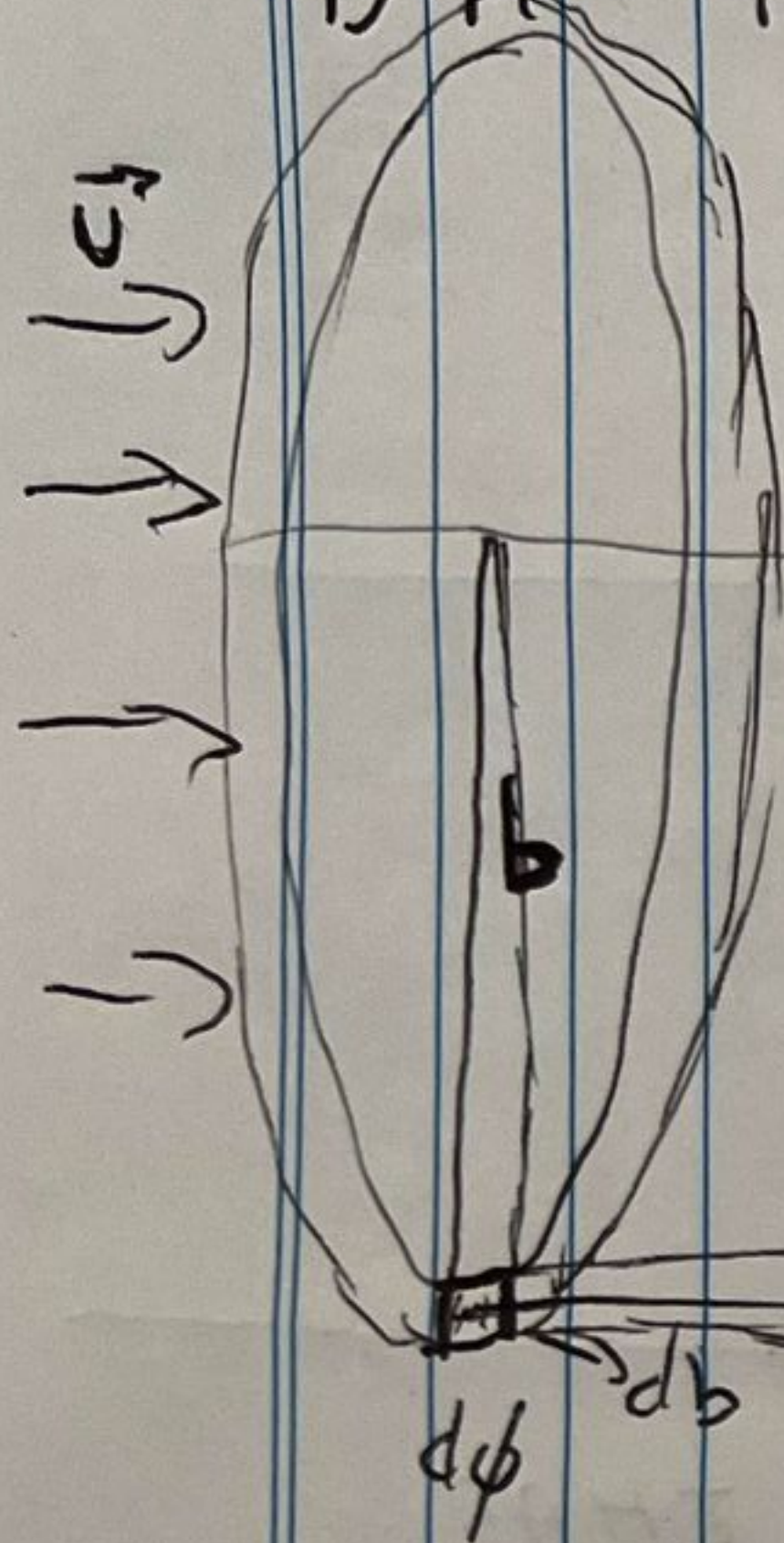


# CAPTURE OF DM IN STARS AND DD RATES

DM FLUX



$$\frac{d\#}{dt} = \frac{P_{\odot}}{m_{\odot}} b db d\phi u$$

$$\frac{b}{r} = b \cdot u = \omega r \sin \theta$$

$$\dot{r} = \frac{dr}{dt} = \omega \cos \theta$$

$$\sin \theta = y$$

$$b db = \frac{\omega^2 r^2}{u^2} y dy$$

$$\frac{1}{2} m u^2 = \frac{1}{2} m \omega^2 r^2 - \frac{GMm}{r}$$

$$\frac{1}{2} m u^2 = \frac{1}{2} m \omega^2 + \frac{1}{2} m v_e^2$$

$$\omega^2 = u^2 + v_e^2$$

$$d\# = 2 \frac{P}{m} b db d\phi u \cdot \frac{dr}{\dot{r}}$$

$$= 4\pi \frac{P}{m} b db u \frac{dr}{\dot{r}}$$

$$\sin \theta = \frac{bu}{\omega r}$$

$$\cos \theta = \sqrt{1 - \frac{b^2 u^2}{\omega^2 r^2}} = \sqrt{1 - y^2}$$

$$d\# = 4\pi \frac{P}{m} \frac{\omega^2 r^2}{u^2} \frac{y dy}{\sqrt{1-y^2}} \frac{dr}{u}$$

$$d\# = \left[ \frac{P}{m} \cdot 4\pi v^2 dr \frac{\omega}{u} \int_0^1 dy \frac{y}{\sqrt{1-y^2}} \right]$$

$$R = \frac{d\#}{dt} = \frac{P}{m} \cdot \underbrace{4\pi r^2 dv}_{dv} \cdot \underbrace{\frac{W}{U}}_{\text{GRAV. FOCUSING}} \cdot \underbrace{\Omega^-}_{\text{INT. RATE}}$$

DD  $v_e \sim 0 \Rightarrow \frac{P}{m} dV \cdot 1 \cdot \Omega^-$

SPEED DISTR.  $f(u) \quad \int f(u) du = 1$

$$R = \frac{P}{m} 4\pi r^2 dv \int du f(u) \frac{W}{U} \Omega^-$$

INT. RATE

$$\Omega^- = n_T \cdot W \cdot \sigma_{\text{eff}}^T$$

$$\sigma_{\text{eff}}^T = \int_D d\omega \omega \frac{d\sigma^T}{d\omega \omega}$$

D: DOMAIN THAT ALLOWS CAPTURE

KIN. VAR

- $\vec{S}$  speed of c.o.m.
- $\vec{U}$  x speed cm c.o.m. F.
- $\vec{W}$  x speed lol f.
- $\vec{V}$  N speed lol f.

$$N = \frac{m_x}{m_T}$$

$$N_{\pm} = \frac{N \pm 1}{2}$$

$$\vec{s} = \frac{n\vec{w} + \vec{v}_n}{1+n}$$

$$\vec{t} = \frac{\vec{w} - \vec{v}_n}{1+n}$$

$$\vec{w} = \vec{s} + \vec{t}$$

$$\cos \theta_{st} = \frac{w^2 - s^2 - t^2}{2st}$$

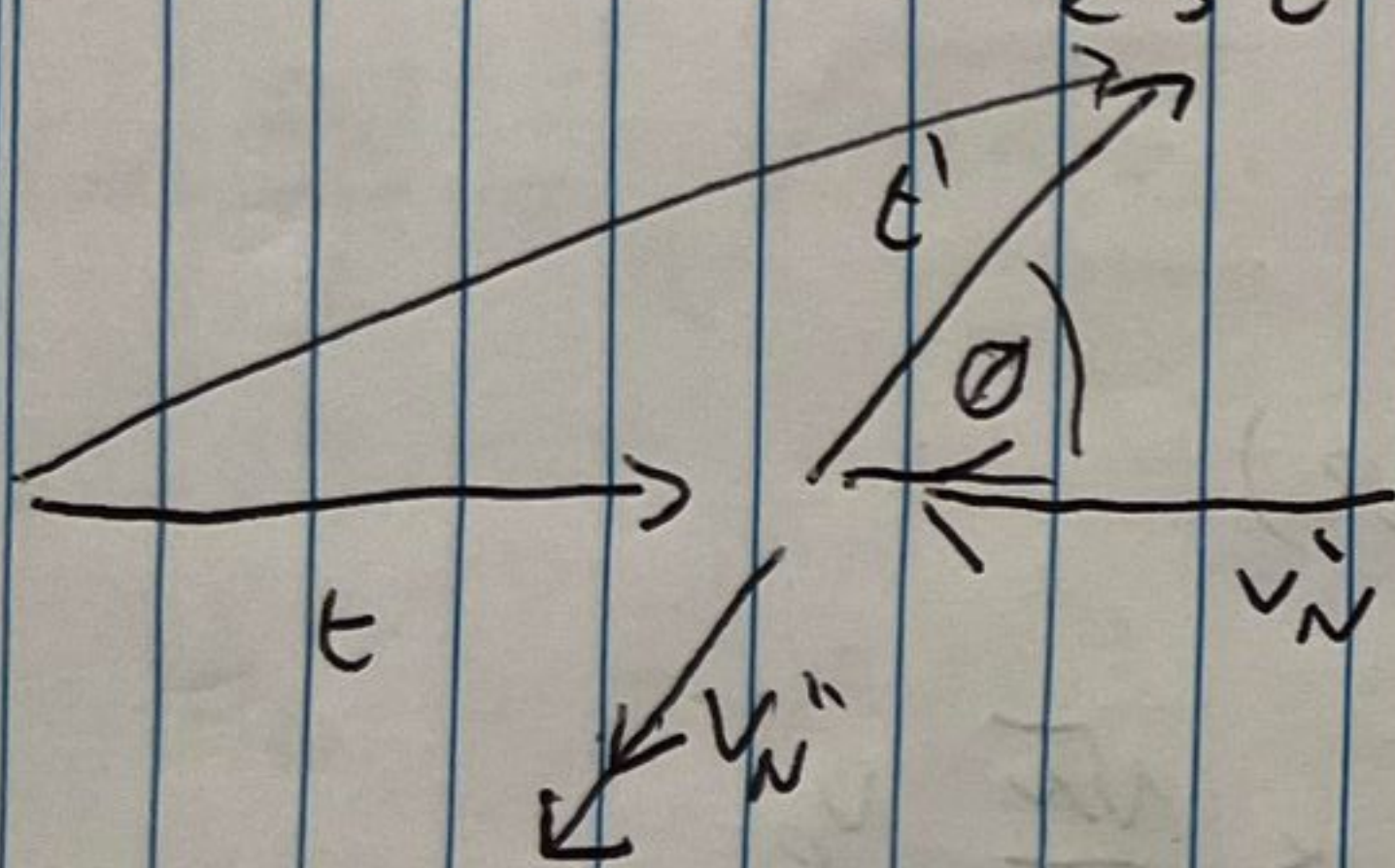
$$T \rightarrow 0 \Rightarrow v_n \rightarrow 0 \Rightarrow$$

$$s = \frac{n}{1+n} w$$

$$t = \frac{1}{1+n} w$$

$$\cos \theta_{st} \rightarrow 1$$

$$\theta_{st} = 0$$



$$\theta = \theta_{st}$$

$$\vec{v} = \vec{s} + \vec{t}$$

$$\cos \theta_{st} = \cos \theta$$

$$\frac{v^2 - s^2 - t^2}{2st} =$$

$$\frac{v^2(1+n)^2 - w^2(1+n^2)}{2n w^2}$$

$$\Omega = n_T w \int d\cos \theta \frac{d\sigma}{d\cos \theta}$$

CHANGE

$$d\cos \theta = \frac{2v dv (1+n)^2}{2nw^2} = \frac{4n_T^2}{n} \frac{v dv}{w^2}$$

$$= m_T w \frac{4n_T^2}{nw^2} \int v dv \frac{d\sigma}{d\cos \theta}$$

$$D = ?$$

$$v_{max} = v_e \cos \theta = \frac{v_e^2(1+n)^2 - (v_e^2 + v^2)(1+n^2)}{2nw^2} < 1$$

$$v_e^2(1+n)^2 - (v^2 + v_e^2)(1+n^2) < 0 \quad v$$

$$\cos \theta_{st} > -1 \Rightarrow \frac{v^2 (1+n)^2 - w^2 (1+n^2)}{2nw^2} > -1$$

$$v^2 (1+n)^2 - w^2 (n-1)^2 > 0 \Rightarrow v^2 > \frac{n^2}{n+2} w^2 \Rightarrow v > \frac{n-1}{n+2} w$$

$$Q = \int_{\frac{n-1}{n+2} w}^{v_e} v dv \cdot n_T \frac{4M_T^2}{nw} \frac{d\sigma}{d\cos\theta}$$

$$\Rightarrow \text{REQUIRES } v_e > \frac{n-1}{n+2} w \Rightarrow v_e^2 > \frac{n^2}{n+2} (v_0^2 + w^2)$$

$$\Rightarrow v_e^2 \left(1 - \frac{n^2}{n+2}\right) > v^2 \Rightarrow v_e^2 \frac{n}{n+2} > v^2 \Rightarrow v < \frac{\sqrt{n}}{n+2} v_e$$

SAMPLE LOW v

$$C = \frac{P}{M} \int_0^R 4\pi v^2 dv \int_0^{\frac{\sqrt{n}}{n+2} v_e} dv f(v) \frac{w}{v} \cdot n_T \frac{4M_T^2}{nw} \int_{\frac{n-1}{n+2} w}^{v_e} v dv \frac{d\sigma}{d\cos\theta}$$

$$\int_0^{\frac{\sqrt{n}}{n+2} v_e} dv \frac{f(v)}{v}$$

DIRECT  
DIFFERENT

DET.  
VARIABLE

$$\theta \rightarrow E_R$$

$$E_R = \frac{q_{tr}^2}{2m_T}$$

$$q_{tr} = 2t \cdot m \sin \frac{\theta_{sc'}}{2}$$

$$q_{tr}^2 = 4m^2 t^2 \left(1 - \cos^2 \frac{\theta_{sc'}}{2}\right)$$

$$\cos \frac{\theta_{sc'}}{2} = \sqrt{\frac{1 + \cos \theta_{sc'}}{2}}$$

$$\Rightarrow q_{tr}^2 = 4m^2 t^2 \left(1 - \frac{1 + \cos \theta}{2}\right) = 2m^2 t^2 (1 - \cos \theta)$$

$$T \rightarrow 0 \quad q_{tr}^2 = 2m^2 \frac{\omega^2}{(1+N)^2} (1 - \cos \theta) = \frac{2m_x^2 m_T^2 \omega^2}{(m_0 + m_N)^2} (1 - \cos \theta) = 2N_{Tx}^2 \omega^2 (1 - \cos \theta)$$

$$E_R = \frac{q_{tr}^2}{2m_T} = \frac{m_x^2 m_T \omega^2}{(m_T + m_x)^2} (1 - \cos \theta) \quad dE_R = - \frac{m_x^2 m_T \omega^2}{(m_T + m_x)^2} d(\cos \theta)$$

$$E_R^{MAX} = \frac{2m_x^2 m_T \omega^2}{(m_T + m_x)^2}$$

$$\Omega^- = m_T \omega \int_{E_R^{MIN}}^{E_R^{MAX}} \frac{(m_T + m_x)^2}{m_x^2 m_T \omega^2} dE_R \quad \frac{d\theta^+}{d(\cos \theta)}$$

$$\frac{dR}{dE_R} = \frac{P}{m_x} \int du f(u) \underbrace{\frac{dV}{N_T}}_{N_T} \frac{(m_x + m_N)^2}{m_x^2 m_T} \frac{d\sigma}{d\cos\theta}$$

$$M_T = m_T N_T$$

$$\frac{d\bar{R}}{dE_R} (E_R) = \frac{P}{m_x} \int du \frac{f(u)}{u} \frac{(m_x + m_N)^2}{m_x^2 m_T} \frac{d\sigma}{d\cos\theta}$$

$$E_R < E_R^{\max} = \frac{2m_x^2 m_T u^2 \rightarrow u^2}{(m_T + m_x)^2} = \frac{2m_x^2 m_T u^2}{(m_T + m_x)^2}$$

$$\Rightarrow u^2 > \frac{(m_T + m_x)^2 E_R}{2m_x^2 m_T} = \frac{E_R \cdot m_T}{2M_T^2} = u_{\min} = v_{\max}(E_R)$$

$$\Rightarrow \int_{u_{\min}}^{u_{\max}} du \frac{f(u)}{u} \Rightarrow \text{SAMPLE CARTE } u$$

$$\frac{d\sigma^T}{d\cos\theta} = \frac{1}{32\pi} \frac{|M_T|^2}{(m_x + m_N)^2}$$

$$|M_T|^2 = \frac{m_T^2}{m_N^2} \cdot C_i^N C_j^N F_{ij}^N$$

$C_i^N C_j^N$  → COEFF NREFT OP.  
 $F_{ij}^N$  → FORM FACTORS